

Modelling of **Cyber-Physical Systems** through **Domain-Specific Languages**: **Decision**, **Analysis**, **Design**

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When and How to Develop DSLs

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Modelling of CPS in DSL Decision, Analysis, Design

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Abstract

Cyber-Physical Systems (CPS) integrate computational algorithms and physical components, requiring sophisticated modelling techniques to address complex interactions and dynamics. This paper explores the creation of Domain-Specific Languages (DSLs) tailored for CPS, focusing on the initial three critical phases: decision, analysis, design. We present four key aspects to address in the decision phase, design an ontology as ^a domain model for the analysis phase, Plutse, uestgu an ontology as a normal moved on the commercially and collect some advice for the design phase. By systematically addressing these phase by the design phase. By systematically
for developing DSLs that can efficiently model circlessive framework
improved design, verification controlly model CPS formework improved design, verification, and deployment e^Cs, facilitating
systems. Improved design, verification, and deployment of these intricate

CCS Concepts

• Software and its engineering → Domain specific languages;
^{Interoperability; Design languages; • Informatic.
'0logies: • Notware'} *Interoperability*; *Design languages*; **• Information systems** \rightarrow **On**tologies; • Networks \rightarrow Network protocol design.

Keywords

Cyber-Physical Systems, Ontological Analysis, Domain-Specific

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for performance of the first particle of the community of ACM ISBN 979-8-4007-0622-6/24/09
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Enschede, The Netherlands ¹ Introduction Cyber-Physical Systems (CPS) represent collaborations of computational algorithms and physical components [61], creating ^a net-Work where digital systems monitor and control physical processes through sensors and actuators. These systems form ^a feedback loop where sensor data informs computations form a feedback
tuators execute these decisions computational decisions, and ac-
Examples of CRP decisions to affect the all decisions, and ac-Examples of CPS include smart grids, autonomous vehicles, and we wise we will develop the physical environment. advanced medical monitoring systems [66, ⁸³]. CPS hold substan-

tial potential across diverse domains such as smart manufacturing,
tobotics, healthcare, intelligent transportation, and smart critics,
offering benefits like enhanced automation, and smart critics,
optimised resource usa rai potential actions turelate outlined by our as situate individually robotics, healthcare, intelligent transportation, and smart cities, offering benefits like enhanced automation, and smart cities
optimised resource usage [35, 42, 61, 72].
Realising the full not all posters and the state of safety, and P -minsed resource usings $[1\ldots, 2\ldots, \ldots]$.
Realising the full potential of CPS poses significant challenges due to their inherent complexity and heterogeneity [83]. Integrat-

ing the continuous, concurrent physical world with the discrete, sequential cyber world often leads to non-deterministic behaviours, complicating the development of reliable and dependable models. Model-Driven Engineering (MDE) addresses these complexities by breaking down CPS into manageable components, yet the intricacies of such systems demand specialised modelling approaches [22]. des vi survi systems ucumunt speciativen invincing approvatives [ev];
Domain-Specific Languages (DSLs) offer a promising solution for CPS modelling by providing tailored notations and constructs
specific to the domain [23, 87]. Unlike generalions and constructs
(GPLs) DNI p.e. (GPLs), DSLs can encapsulate domain-specific knowledge languages
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domain experts and developers [59]. For instead of the well-known and developers [59]. For instead of the well-known are well-known DSLs in their respective domains.
It is known from prior well at the respective domains. It is known trong the west that DSL development can be concep-

tually split into phases of decision, analysis, design and implementation [60]. By addressing these phases, we wish to provide a comprehensive framework for developing DSLs that can to provide a
model CPS. Essentially we want the answers to the Can efficiently
search questions: model CPS. Essentially we want the answers to the following re-RQ1: What are critical aspects that DSLs must address to ensure

that modelling and implementation of CPS to be most effective? RQ2: How can we analyse and model the CPS domain to understand the foundational concepts and model the CPS domain to under
these systems?
These systems?

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When and How: Phases

Why DSL?

- domain-specific abstractions
- domain-specific notations
- separation of concerns
- tool support
- conciseness/self-documentation
- productivity/maintainability
- reliability & …ilities
- conservation/reuse of domain knowledge
- executability/liveness
- involvement/collaboration
- shorter lifespan

CEUR: [2707.5](https://ceur-ws.org/Vol-2707/oopslepaper5.pdf)

Decision Phase

- **domain**
	- catering, lithography, music, grammars
- **codomain**
	- ecosystem, platform, integration
- **paradigm**
	- declarative, interactive, traversal-driven
- **purpose**
	- automation, visualisation
- **approach**
	- visual, textual, API, library

Decision

- **interoperability**
	- specify how components work together
- **behaviour**
	- define the flow of operation
- **timing**
	- delays, deadlines, sheduling
- **discrete&continuous**
	- physical process vs computation

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Analysis Phase

- **terminology**
	- concepts, aspects, definitions
- **knowledge**
	- capture, representation, management
- **methodology**
	- DARE, DSSA, FAST, FODA, ODE, ODM, …
- **models**
	- ontology, feature model
- **formal** vs **informal**
	- text, diagrams, algebra, logic

Analysis

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Analysis

Design Phase

- **language exploitation**
	- piggyback, specialise, extend, invent
- **informal design**
	- text, natural models, examples of model instances
- **formal design**
	- grammars, abstract state machines
- **features**
	- what to include, how to support

Design


```
normal \rightarrow sensor\_failurewhen E = 0 and S \neq 0Knormal \rightarrow high_temperature
     when E = 0 and S = OK and T > 30
normal \rightarrow system_error when E = 1
```
 $E = 1$ \Rightarrow $D = system_failure$ $S \neq \mathbf{0}K \Rightarrow D =$ sensor_failure $T > 30 \implies D = high_t$ temperature

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Conclusion

https://zorro-project.nl/

- making a **DSL** is a complex process
- **decision** phase: what's important?
- **analysis** phase: what's the domain?
- **design** phase: which features?
- we did the first steps for **CPS**

Modelling of Cyber-Physical Systems through Domain-Specific
Languages: Decision, Analysis, Design Languages: Decision, Analysis, Design
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 h h m.gerhold@utwente.nl Formal Methods and Tools a.kouzel@student.utwente.nl Haroun Mangal h.mangal@student.utwente.nl University of Twente Technical Computer Science Enschede, The Netherlands University of Twente Technical Computer Science Enschede, The Netherlands University of Twente Selin A. Mehmed $$\rm\,Enschede, The Netherlands\rm\,Valim\,Zautser.$ s.a.mehmed@student.utwente.nl Technical Computer Science v adim@grammarware.net University of Twente Formal Methods and Tools Enschede, The Netherlands University of Twente Abstract Enschede, The Netherlands Cyber-Physical Systems (CPS) integrate computational algorithms and physical components, requiring sophisticated modelling tech-¹ Introduction niques to address complex interactions and dynamics. This paper Cyber-Physical Systems (CPS) represent collaborations of compuexplores the creation of Domain-Specific Languages (DSLs) tailored tational algorithms and physical components [61], creating ^a netfor CPS, focusing on the initial three critical phases: decision, analwork where digital systems monitor and control physical processes
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cyber physical systems Methods & Tools